Lecture 7 summary

Stationary solution of master equation pr

Rak equations for  $\langle N(t) \rangle = \sum_{n=0}^{\infty} n p_n(t)$   $\langle N(t) \rangle = \langle g_n \rangle - \langle r_n \rangle$   $\langle N \rangle = -\gamma \langle N \rangle$  linear decay (see example of radioactive decay of N/t/ atoms, lecture 6)

Example: Chemical reaction X = A

- · master equation  $\dot{p_n} = \cdots$
- generating function  $\partial_{\mu} G(s, t) = \dots$   $G(s, t) = \dots$
- · moment equations

 $\frac{d}{dt} < N(t)^{k} / f = k \left[ \kappa_{z} \alpha \left( N(t) \right)^{k-1} - \kappa_{1} \left( N(t)^{k} \right) \right]$ further the moment

2.2 Fokker-Planck equation (FPE)

Here we will descess the theory of continuous Markov processes from the point of view of FPE, which gives the time evolution of the probability density function for the system.

In one dimension  $\rightarrow$  18 random variable x(t)  $\frac{\partial}{\partial t} f(x,t) = -\frac{\partial}{\partial x} \left[ A(x,t) f(x,t) \right] + \frac{1}{2} \frac{\partial^2}{\partial x^2} \left[ B(x,t) f(x,t) \right]$  drift

We have previously shown (see lecture 5) that FPE is valid for conditional probability

$$f(x, t) = p(x, t/x, t)$$

for any initial

Xo, to, and initial condition

However, using definition of one time probability  $p(x,t) = \int dx_{o} p(x,t;x_{o},t_{o}) =$   $= \int dx_{o} p(x,t|x_{o},t_{o}) p(x_{o},t_{o}),$ 

we see that it is also valid for  $p(x_1t)$  with J.C.  $p(x_1t) = p(x_1t_0)$ , which is generally less singular them. (\*).

## Boundary conditions

FPE 1s a second order parabolic PBE, and for solutions we need I.C. and boundary conditions (B.C.) at the end of the Interval inside which X is constrained. These B.C. take on a variety of forms.

It is simple to derive the B.C. in general, then to restrict consideration to the one variable situation.

## n - dimensional boundary conditions

We consider the forward FPE
$$\frac{\partial_{t}}{\partial t} p(\vec{x}, t) = - \underbrace{\sum_{i} \frac{\partial}{\partial x_{i}}}_{\partial x_{i}, \partial x_{i}} B_{ij}(\vec{x}, t) p(\vec{x}, t) + \frac{1}{2} \underbrace{\sum_{i,j} \frac{\partial^{2}}{\partial x_{i}, \partial x_{j}}}_{\partial x_{i}, \partial x_{j}} B_{ij}(\vec{x}, t) p(\vec{x}, t)$$

We note that this can be written

$$\frac{\partial}{\partial t} p(\vec{x},t) + \leq \frac{\partial}{\partial x_i} J_i(\vec{x},t) = 0 \quad (**)$$

where we define the probability current

$$\vec{J}_{i}(\vec{x},t) = A_{i}(\vec{x},t)p(\vec{x},t) - \frac{1}{2} \underbrace{z}_{j} \frac{\partial}{\partial x_{j}} \left[ B_{ij}(\vec{x},t)p(\vec{x},t) \right]$$

Equation (\*\*\*) has the form of a local conservation equation, and can be written in an integral form as follows. Consider some region R with a boundary of and olefine:

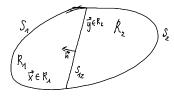
$$P(R,t) = \int d\vec{x} p(\vec{x},t)$$

then (\* \*) is equivalent to

$$\frac{\partial}{\partial t} P(R,t) = - \int_{S} dS \vec{n} \cdot \vec{J}(\vec{x},t) \qquad (x \times x)$$

where it is the outward pointing normal to S.

Thus (\* \* \*) judicates that the total loss of probability is given by the surface integral of I over loundary of R. We can show as well that the current if does have the stronger property, that a surface subsegrel over any surface S gives the net flow of probability across that surface.



The net flow of probability can be computed by noting that we are dealing with a process with continuous sample paths, so that in a sufficiently short time st, the prob. of

erossing S12 from R2 to R1 is the joint probability of leing 14 R2 ex time t and Ry at time test:

$$\int d\vec{x} \int d\vec{y} p(\vec{x}, t+\Delta t; \vec{y}, t)$$

$$R_1 R_2$$

The net flow of prob-ty from R2 to R, 15 oftained by substracting from this the prob-ty of crossing in the processed direction, and dividing by st:

$$\lim_{\Delta t \to 0} \frac{1}{\Delta t} \int_{\Delta t} d\vec{x} \int_{R_1} d\vec{y} \left[ p(\vec{x}, t + \Delta t; \vec{y}, t) - p(\vec{y}, t + \Delta t; \vec{x}, t) \right] =$$

$$= \int_{R_1} dS \vec{x} \cdot \vec{J} (\vec{x}, t)$$

$$S_{12}$$

n points from R, to R.

Boundary conditions

(a) Reflecting barrier

The positicle cannot leave R bence there is zero net flow of prob. across S, the boundary of R.  $\vec{\lambda} \cdot \vec{J}(\vec{x}, t) = 0$  for  $X \in S$ ,  $\vec{n} = \text{normal } t \circ S$ .



Since the particle cannot cross S, it must be reflected there, = reflecting barrier

(b) Absorbing barrier

particle reaches S =7 it is removed from

the system, thus the barrier absorbs => the prob-ty of being on the boundary is zero;

$$P(\vec{x}, t) = 0$$
 for  $\vec{x} \in S$   $J \rightarrow J$ 

(c) Boundary conditions at a discontinuity (medium 1 and medium 2

Separated by S)

$$A^{(1)}, B^{(1)} | A^{(2)}, B^{(2)} | \vec{n} \cdot \vec{J}(\vec{x})|_{S_{+}} = \vec{n} \cdot \vec{J}(\vec{x})|_{S_{-}}$$

$$p(\vec{x})|_{S_{+}} = p(\vec{x})|_{S_{-}}$$

St, S. mean the Croits of the guardities from the left and right hand sides of the surface.

The definition of the prob. current indicates that the derivatives of  $p(\vec{x})$  are not necessarily continuous at S.

(d) periodic boundary could from

[a, b] the two end points are identified with each other

We impose boundary could trans

derived from those for a discontinuity:



I: 
$$\lim_{x \to b_{-}} P(x_{i}t) = \lim_{x \to a_{+}} P(x_{i}t)$$

$$I\underline{T}: \lim_{k\to \underline{b}} J(x_i t) = \lim_{k\to a_+} J(x_i t)$$

Most frequently, periodic B.C. are suposed when the functions A(x, t) and B(x, t) are periodic or the same surfaces:

$$A(b_i +) = A(a_i +)$$

$$\beta(\ell,t)=\beta(a,t)$$

## (e) Natural boundary

$$A(a,t)=0$$

The particle, once it reaches x=a, will remain there.

It can be , however, demonstrated it cannot ever reach this point.

This is a boundary from which we can wither absorb nor at which we can introduce any particles.

Stationary solutions for homogeneous FPE

hom. process: drift and doffusion coefficients are time independent.

$$\frac{d}{dx} \left[ A(x) p^*(x) \right] - \frac{1}{2} \frac{d^2}{dx^2} \left[ B(x), p^*(x) \right] = 0$$

and in terms of current

$$\frac{d}{at} J(x) = 0$$

=> solution J(x) = court

Suppose the process takes place on an interval (a, b). Then we must have:

$$J(a) = J(x) = J(b) \equiv J$$

and if one if the boundary cond is reflecting, this means that both one reflecting and J=0.

If the B.C. are not reflecting @ requires them to be periodic.

(i) Zero current - potential solution

$$A(x) p^*(x) = \frac{1}{2} \frac{d}{dx} \left[ B(x) p^*(x) \right] = 0$$

the solution

$$p^*(x) = \frac{\mathcal{N}}{B(x)} \exp \left[ 2 \int_a^x dx' \frac{A(x')}{B(x')} \right]$$

$$N$$
 - hormalization constant 
$$\int_{a}^{b} dx p^{*}(x) = 1$$

Such a solution is known as potential solution because the stationary solution is obtained by a single jutegration.