

D-befurcation (dynamical) - change of stability of trajectories belonging to a certain set with a given measure (inversant). For example, a sign change of one of the hyapunor exponents.

3.4.3 Coherence resonance in Squart-Landon oscillator

Ushakov et al. Phys. Rev. Lett 35, 2005

Stuart-Landau oscillator

Z is complex variable

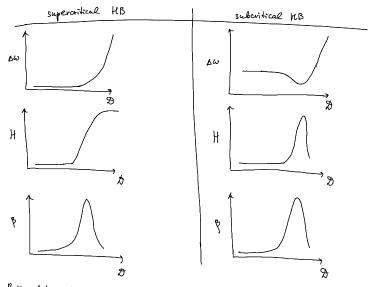
$$F(z) = a_1 - |z|^2$$
 supercritical HB

$$F(z) = a_z + |z|^2 - |z|^4$$
 subcritical HB

$$r = |2| = \sqrt{x^2 + y^2}$$

Measure of CR -> signal-to-noise ratio (SNR)

(R occurs in a strict sense only in the subcritical case



Both bifurcations demonstrate resonance - like Rehaviour.

Supercritical -> DW increases as $\sqrt{3}$ at larger \mathcal{D}_{j}^{*}

peak height H grows juitfelly like H~D and Saturetes for stronger noise

Suboritical -> Day is non-monotonic with a distinct minimum at a certain noise level peak height H has a clear maximum.

Supercritical case \rightarrow the sucrease of SNR is produced by the spectral peak leight H, that is by an increase of the oscillation amplitude. The width ace is suitially only weakly affected, but sucreases sleeply for stronger hope weakening the coherence. The vesonance in $\beta \rightarrow$ due to competition between the growth of H and so.

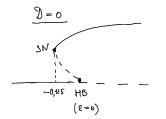
Subcritical case -> Do itself demonstrates a minimum -> noise improves, indeed the temporal coherence of oscillations.

3.4.4. Duffing - van der Pol oscillaton

Zakharova et al. Phys. Rev. E 2010

$$\ddot{X} - (\mathcal{E} + X^2 - X^4)\dot{X} + X + \beta \ddot{X}^5 = \sqrt{2}\mathcal{D} n(t)$$
, $\beta > 0$
 $n(t)$ is Gaussian white noise: $\langle n(t) n(t+\tau) \rangle = \mathcal{O}(\tau)$
 $\langle n(t) \rangle = 0$
 ∂ is noise intensity

 β defines anisochronicity of oscillations: $\beta=0$ \Rightarrow system is isochronous \rightarrow the frequency of oscillations does not depend on the amplitude.



 $-\frac{1}{8}$ < ε < 0 (between SN and HB) bistability: stable focus + stable LC

Analytical approach: we assume that & is small - fluctuations of the amplitude and phase are "slow" stochastic processes.

=> they remain unchanged during the period $T_o = 2\pi$ ($\omega_o = 1$)

We change vourables:

$$x(t) = a(t) \cos \left[t + \varphi(t) \right], \dot{x}(t) = -a(t) \sin \left[t + \varphi(t) \right]$$

a (+) - instantaneous amplitude

V(t) - instantaneous phase

We substitute new variables into the equation of D.-vander Poloscillator and average the equations over the period of oscillations.

[see details of the method in R.L. Stratohovich, selected Topics in the Theory of Random Noise 1963, vol. 1 and 2]

We obtain stochastic equations for the slow random variables:
$$\dot{a} = \left(\frac{\varepsilon}{2} + \frac{a^2}{8} - \frac{a^4}{16}\right)a + \frac{\vartheta}{2a} + \sqrt{\vartheta} n_x(t),$$

$$\dot{q} = \frac{3\beta}{8}a^2 + \frac{\sqrt{\vartheta}}{a} n_z(t),$$

$$n_x(t) \text{ and } n_z(t) \text{ are independent sources of Gaussian white noise}$$

From these equations we can devive the amplitude of stable limit cycle for $\delta = 0$: $q_o = \sqrt{1 + \sqrt{1 + 8 \epsilon}}$

An important observation -> a does not depend on 10 =>

=7
$$p(\alpha,t)$$
 rather than $p(\alpha, y, t)$

joint probability density for y and y

$$\dot{\alpha} = \left(\frac{\varepsilon}{2} + \frac{\alpha^2}{8} - \frac{\alpha^4}{16}\right) \alpha + \frac{9}{2\alpha} + \sqrt{9} \eta_1(4)$$